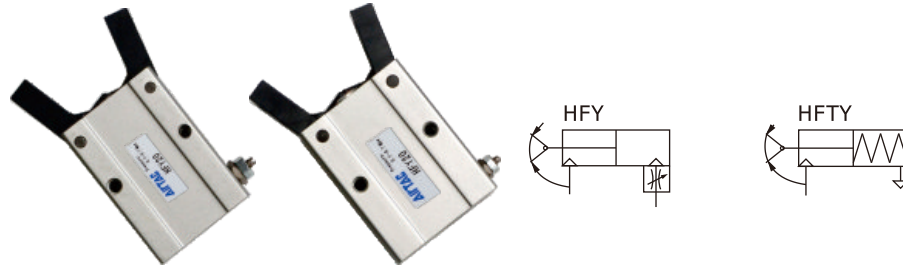




Air gripper—HFY Series

Angular style



Ordering code

HFY 20

① ②

① Model

HFY: Air finger(Angle style, Double acting)

HFTY: Air finger(Angle style, Single acting and normally opened)

② Bore size

6 10 16 20 25 32

[Note] HFY series are all attached with magnet.

Specification

Bore size (mm)		6	10	16	20	25	32
Acting type		Double acting			Single acting		
Fluid		Air(to be filtered by 40μm filter element)					
Operating pressure	Double acting	22~100psi(0.15~0.7MPa)					
	Single acting	Φ6	45~100psi(0.3~0.7MPa)				
Φ10~Φ32		36~100psi(0.25~0.7MPa)					
Temperature		-20~70℃					
Lubrication		Cylinder: Not required; Gripper jaws: Lubricate grease					
Cushion type		Bumper					
Max. frequency		180(c.p.m)					
Sensor switches [Note1]		CMSG/DMSG(S)					
Port size		M3×0.5			M5×0.8		

[Note1] Sensor switch should be ordered additionally.

Gripping force and stroke

Acting type		Double acting(HFY)						Single acting Normally opened(HFTY)					
Bore size		6	10	16	20	25	32	6	10	16	20	25	32
Theoretical gripping torque (N·cm)	Closed	7.4×P	17.6×P	90×P	152×P	304×P	637×P	5.7×P	11.8×P	71.2×P	122.4×P	252×P	589×P
	Opened	10.6×P	29.4×P	129×P	252×P	473×P	904×P	-	-	-	-	-	-
Max. length of gripping point (L)(mm)		30	30	40	60	70	85	30	30	40	60	70	85
Opening angle (°)								30 ⁺³ ₀					
Closing angle (°)								-10 ⁰ ₋₃					

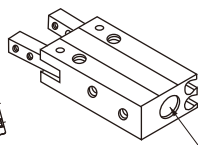
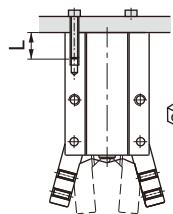
[Note] The P in the gripping torque shown in the above chart represents the actual use of air pressure.



Installation and application

1. Due to the abrupt changes, the pressure is low, which will lead to the decrease of the gripping force and falling of the work-pieces. In order to avoid the harm to the human body and damage to the equipment, anti-dropping device must be equipped.
2. Don't use the air gripper under strong external force and impact force.
3. When install and fix the air gripper, avoid falling down, collision and damage.
4. When fixing the gripping jaw parts, don't twist the gripping jaw.
5. There are several kinds of installation method, and the torque of fastening screw must be within the prescribed moment range shown in the below chart. If the locking moment is too large, it will cause the dysfunctional. If the locking moment is too small, it will cause the position deviation and fall.

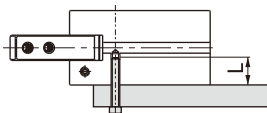
Tail installation type



The bore of the tail is used for mounting and positioning

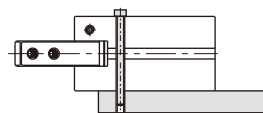
Bore size	The bolts type	Max. locking moment	Max. screwed depth	The aperture of the positioning bore	The depth of the positioning bore
6	-	-	-	Φ7mm ^{+0.04} / _{+0.01}	1.5mm
10	M3×0.5	0.88N.m	6mm	Φ11mm ^{+0.04} / _{+0.01}	1.5mm
16	M4×0.7	2.1N.m	8mm	Φ17mm ^{+0.05} / ₀	1.5mm
20	M5×0.8	4.3N.m	10mm	Φ21mm ^{+0.05} / ₀	1.5mm
25	M6×1.0	7.3N.m	12mm	Φ26mm ^{+0.05} / ₀	1.5mm
32	M6×1.0	7.3N.m	12mm	Φ34mm ^{+0.05} / ₀	2.0mm

The installation of the front threaded hole



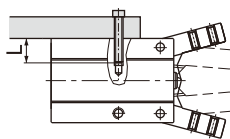
Bore size	The bolts type	Max. locking moment(Nm)	Max. screwed depth(mm)
6	M3×0.5	0.69	5
10	M3×0.5	0.69	5
16	M4×0.7	2.1	7
20	M5×0.8	4.3	8
25	M6×1.0	7.3	10
32	M6×1.0	7.3	10

The installation of the front through hole



Bore size	The bolts type	Max. locking moment(Nm)	Max. screwed depth(mm)
6	M2.5×0.45	0.49	5
10	M2.5×0.45	0.49	5
16	M3×0.5	0.88	7
20	M4×0.7	2.1	8
25	M5×0.8	4.3	10
32	M5×0.8	4.3	10

Surface installation type



Bore size	The bolts type	Max. locking moment(Nm)	Max. screwed depth(mm)
6	-	-	-
10	M3×0.5	0.88	6
16	M4×0.7	1.6	6.5
20	M5×0.8	3.3	8
25	M6×1.0	5.9	10
32	M6×1.0	5.9	10

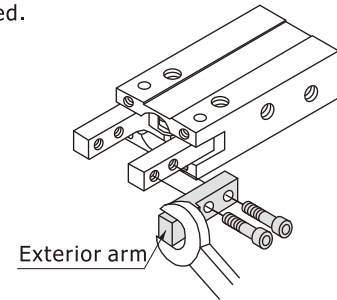
Air gripper(Angular style)

HFY Series

Bore size: $\Phi 6$, $\Phi 10$, $\Phi 16$, $\Phi 20$, $\Phi 25$, $\Phi 32$

6. The installation method of the gripping jaw fittings When install the gripping jaw fittings, you have to pay particular attention that you can only hold the gripping jaw by using spanner, and then lock the screws with allen wrench. Never clamp the body directly and then lock the screws, otherwise the parts will be easily damaged.

Bore size	The bolts type	Max. locking moment (Nm)
6	M2×0.4	0.15
10	M2.5×0.45	0.31
16	M3×0.5	0.59
20	M4×0.7	1.4
25	M5×0.8	2.8
32	M6×1.0	4.9



7. When gripping work-piece, the work-piece must be located in the center line of the two gripping jaws, and the two gripping jaws also need to touch the work-piece at the same time, otherwise they will be easily damaged.
8. Confirm that there is no additional external forces that are exerted on the gripping jaw. Transverse load acts on the gripping jaw, which will cause impact load and leads to the shaking and damage of gripping jaw. Equip with gaps so that the air gripper will not crash into work-pieces and accessories at the end of its trip.
9. When the work-pieces are inserted, the center line should be coaxial, no offset, in case there are external force generated on gripping jaw. When testing, it is specially required that the manual operation should be reduced, the pressure should be used to run it at a low speed, and guarantee the safety and no impact.
10. Please use the flow control valve to adjust the opening and closing speed of gripping jaw if too fast.
11. People can not enter the movement path of air gripper and articles can not be placed on the path too.
12. Before removing the air gripper, please confirm that it is out of working state, and then discharge of compressed air.

How to select product

1. The selection of the gripping force

The gripping work-pieces shown below, on the impact condition of ordinary handling state, taking safety coefficient $a=4$, have a gripping force that is more than 10-20 times of the mass of the gripped objects.

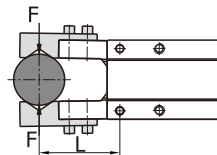
	The work-pieces as shown in the left : F: Gripping force (N) μ : friction coefficient between fittings and work-pieces. m: mass of work-pieces g: acceleration of gravity ($=9.8m/s^2$)	The condition that the work-pieces won't drop is: $2 \times \mu F > mg$ so: $F > \frac{mg}{2 \times \mu}$ Safety coefficient is a, so F is: $F = \frac{mg}{2 \times \mu} \times a$	$\mu = 0.2$	$\mu = 0.1$
			$F = \frac{mg}{2 \times 0.2} \times 4 = 10 \times mg$	$F = \frac{mg}{2 \times 0.1} \times 4 = 20 \times mg$
			10 times of the mass of the gripped objects	20 times of the mass of the gripped objects

Note) If the friction coefficient $\mu > 0.2$, for safety, please also select clamping force according to the principle of 10~20 times of the mass of the clamped objects. As for large acceleration and shock, it requires for greater safety coefficient.

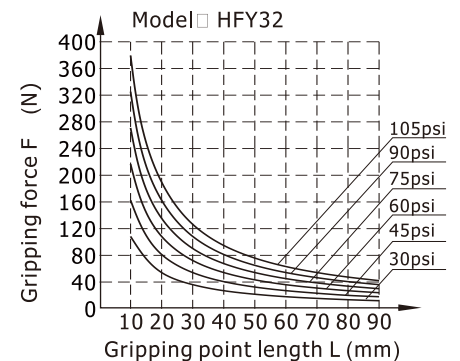
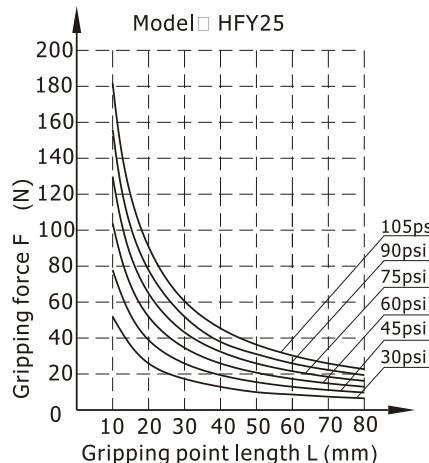
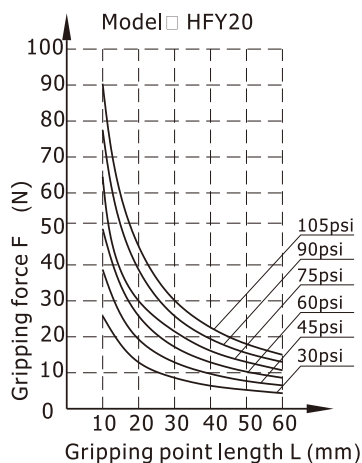
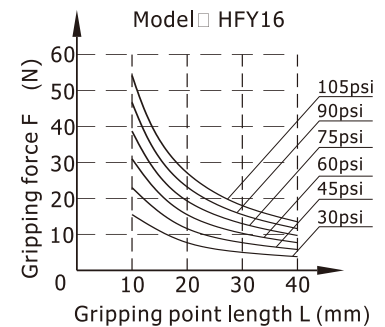
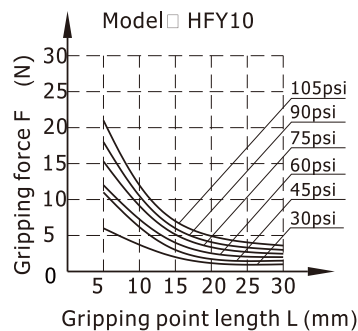
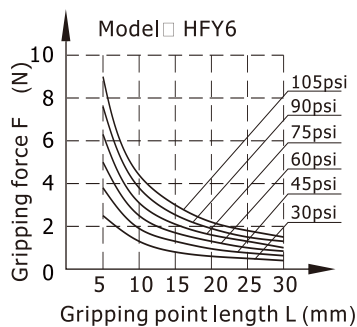
2. The selection of the gripping point

When the gripping force is determined, select the gripping point according to the limitation ranges shown in the below chart. If the gripping point is over the limit, the gripping jaw will be subjected to excessive moment load, and lead to short life of air gripper.

Double acting type closed gripping force



Gripping point length (mm)

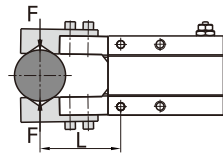


Air gripper(Angular style)

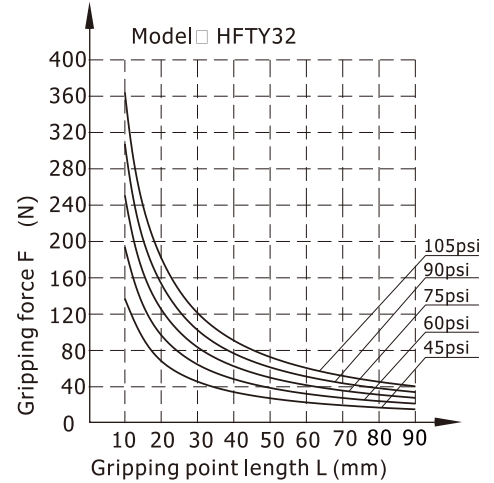
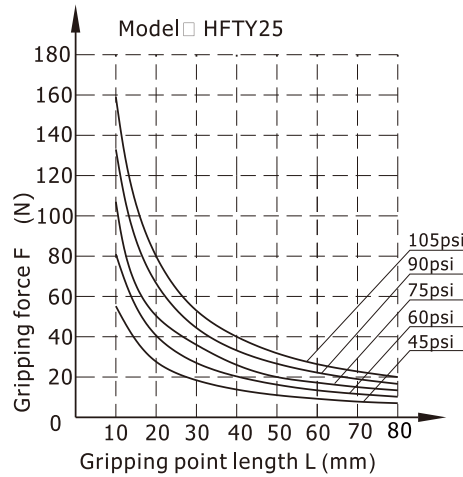
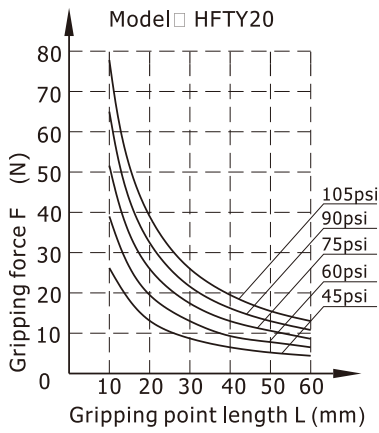
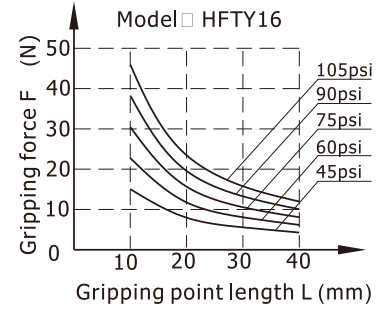
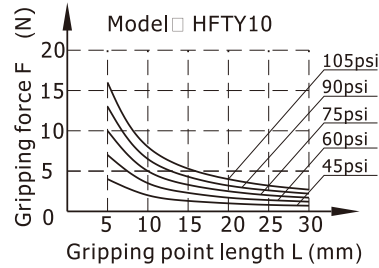
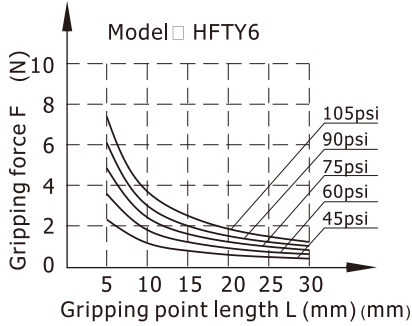
HFY Series

Bore size: $\Phi 6$, $\Phi 10$, $\Phi 16$, $\Phi 20$, $\Phi 25$, $\Phi 32$

Single acting closed gripping force



Gripping point length (mm)

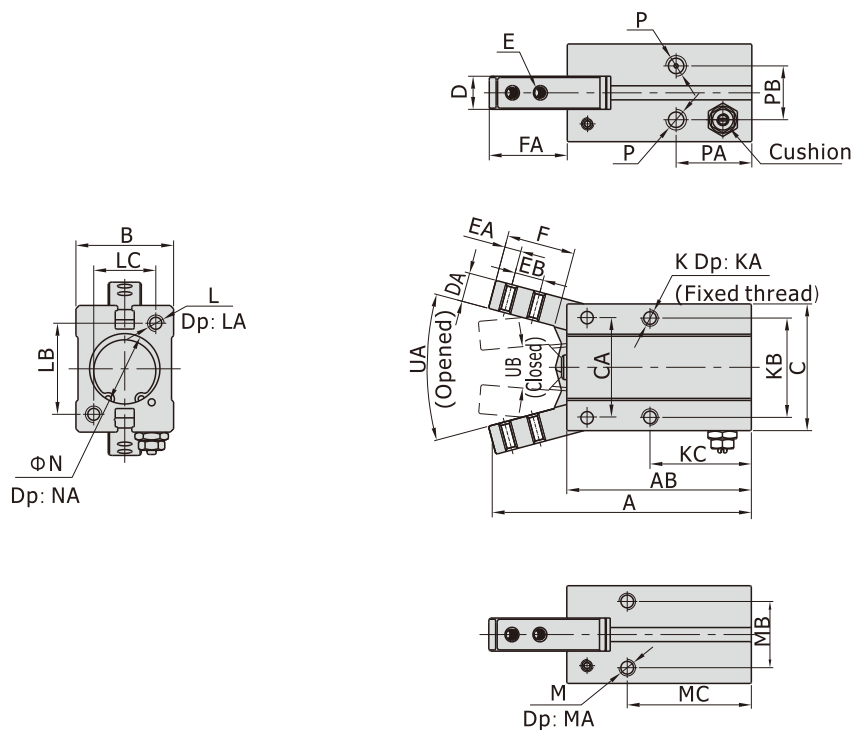


Air gripper(Angular style)

HFY Series

Bore size: $\Phi 6$, $\Phi 10$, $\Phi 16$, $\Phi 20$, $\Phi 25$, $\Phi 32$

Dimensions



[Unit: mm]

Bore size/Item	A	AB	B	C	CA	D	DA	E	EA	EB	F	FA	K	KA	KB	KC	L
6	47.5	36	10.5	20	14	4	4	M2×0.4	2.5	5	11	12	M3×0.5	Thru. thread	12	26	-
10	52.5	38.5	16.5	23	14	6.4	4	M2.5×0.45	3	5.7	12	14.5	M3×0.5	5	16	23	M3×0.5
16	62.5	44.5	23.5	30.5	24	8	7	M3×0.5	4	7	16	19	M4×0.7	7	24	24.5	M4×0.7
20	78	55	27.5	42	30	10	8	M4×0.7	5	9	20	23.5	M5×0.8	8	30	29	M5×0.8
25	92	60.5	33.5	52	36	12	10	M5×0.8	8	12	27	33	M6×1.0	10	36	30	M6×1.0
32	96.5	68	40	60	42	18	10	M6×1.0	6	14	27	29.5	M6×1.0	10	44	37.5	M6×1.0

Bore size/Item	LA	LB	LC	M	MA	MB	MC	N	NA	P	PA	PB	UA(Opened)	UB(Closed)
6	-	-	-	-	-	-	-	$7^{+0.05}_0$	1.5	M3×0.5	19	1.5	30°	10°
10	6	18	12	M3×0.5	6	11.5	27	$11^{+0.05}_0$	1.5	M3×0.5	19	10	30°	10°
16	8	22	15	M4×0.7	8	16	30	$17^{+0.05}_0$	1.5	M5×0.8	18.5	13	30°	10°
20	10	32	18	M5×0.8	10	18.5	35	$21^{+0.05}_0$	1.5	M5×0.8	22	15	30°	10°
25	12	40	22	M6×1.0	10	22	36.5	$26^{+0.05}_0$	1.5	M5×0.8	23.5	20	30°	10°
32	12	46	26	M6×1.0	10	26	30	$34^{+0.05}_0$	2	M5×0.8	31	24	30°	10°